



Smart Materials for Fuzing

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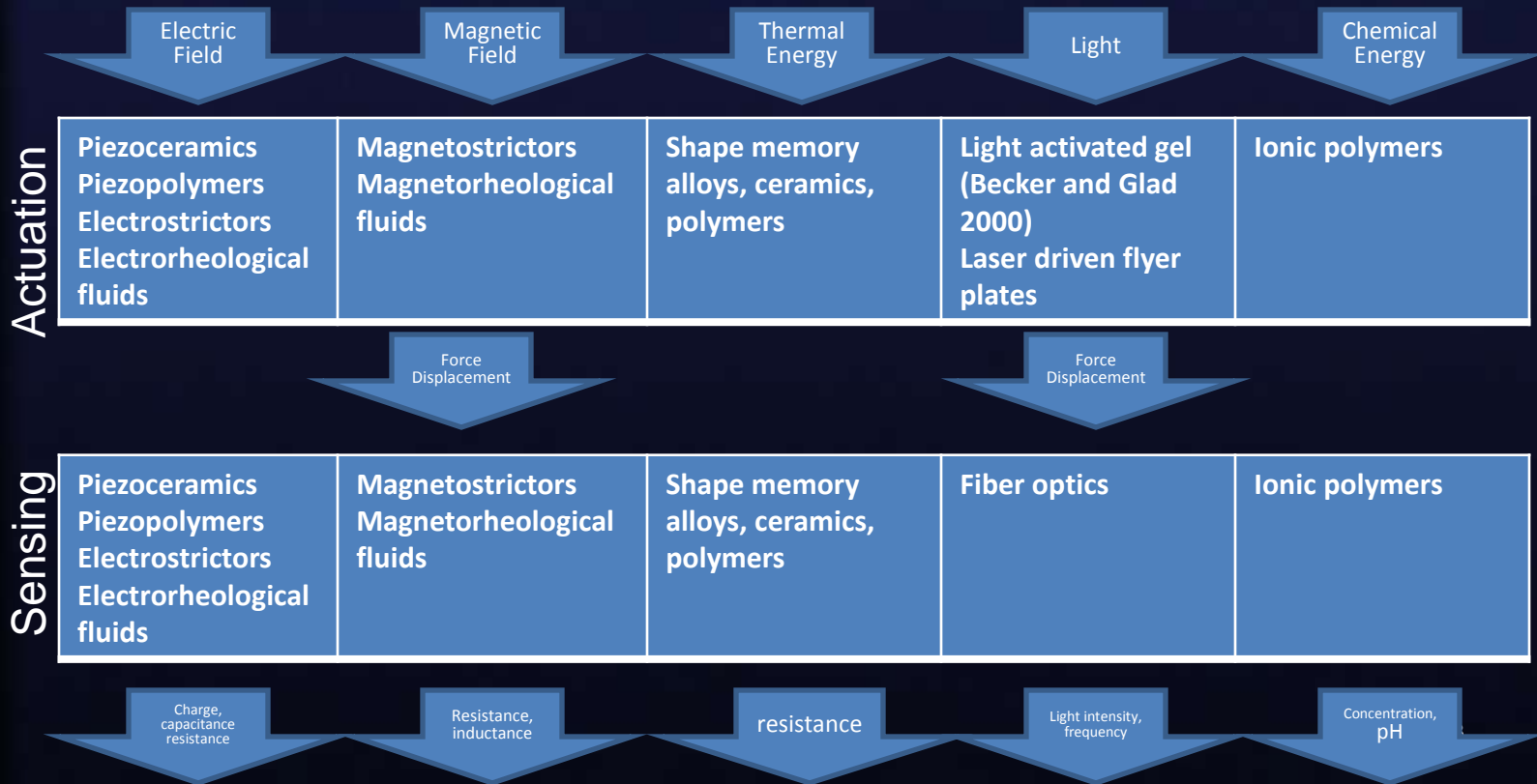
Outline

- Presentation Objective: Review several smart materials and potential applications to fuzing and ordnance
- Smart material overview
- Piezoelectrics
 - *Damage sensing, power harvesting*
- Shape Memory/Superelastic Alloys
 - *IM, self-healing, safe & arm applications*
- Magneto/Electro-rheological Fluid
 - *Suspension, safe & arm*
- Conclusions



Smart Material Classification

- Materials converting energy/fields into other (especially mechanical)
- Many definitions, other names and related areas
 - *Intelligent materials, multifunctional materials*



- Smart structures use these materials to provide integrated sensing, actuation or control and structural integrity



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Why Consider Smart Materials?

- Increased functionality

- *Monitoring functions*

- As munitions age, increased likelihood of malfunctions.
- Sensing solutions can help predict individual or subpopulation reliability

- *Environment sensing*

- Both during storage and at use

- *Adaptivity*

- Shape morphing and control
- Self repair

- Reduced size

- *Higher energy density*

- *Smaller munitions*

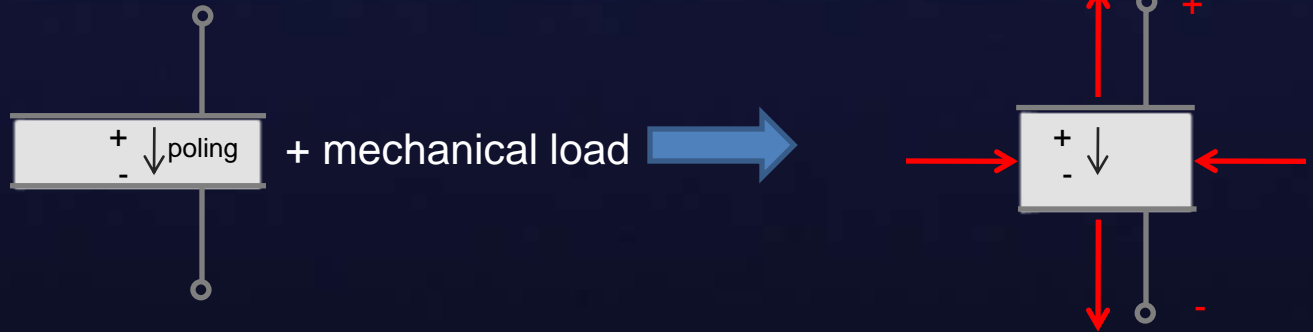
- *Smarter munitions*

- Fit more into the provided space
 - Integrated fuzing guidance and targeting

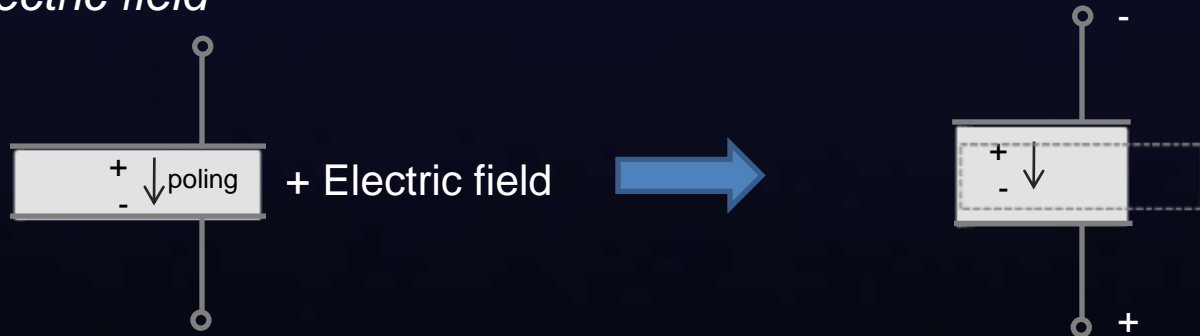


Piezoelectric Background

- Generally high force/ low stroke
- Direct effect
 - *Generates electric charge with applied force*



- Converse effect
 - *Generates mechanical force/ displacement from electric field*



Piezoelectric Material Background

- Piezoelectric effect found in crystals, ceramics polymers and biological materials
- Common piezoceramics lead zirconate titanate (PZT), Barium titanate, lead metaniobate (PMN)
- PZT – high piezoelectric and dielectric constants
 - Many formulations of PZT exist – Hard, soft
- DOD-STD-1376 - Originally defined standard material types for Hydrophones
 - *DOD or Navy Type I- VI*
 - *Hard or soft, Curie point, Self heating susceptibility (high electric drive potential)*
- Manufacturers generally report material properties



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Material Modeling

- 3D constitutive equations

$$\begin{bmatrix} S_1 \\ S_2 \\ S_3 \\ S_4 \\ S_5 \\ S_6 \end{bmatrix} = \begin{bmatrix} s_{11}^E & s_{12}^E & s_{13}^E & 0 & 0 & 0 \\ s_{21}^E & s_{22}^E & s_{23}^E & 0 & 0 & 0 \\ s_{31}^E & s_{32}^E & s_{33}^E & 0 & 0 & 0 \\ 0 & 0 & 0 & s_{44}^E & 0 & 0 \\ 0 & 0 & 0 & 0 & s_{55}^E & 0 \\ 0 & 0 & 0 & 0 & 0 & s_{66}^E = 2(s_{11}^E - s_{12}^E) \end{bmatrix} \begin{bmatrix} T_1 \\ T_2 \\ T_3 \\ T_4 \\ T_5 \\ T_6 \end{bmatrix} + \begin{bmatrix} 0 & 0 & d_{31} \\ 0 & 0 & d_{32} \\ 0 & 0 & d_{33} \\ 0 & d_{24} & 0 \\ d_{15} & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} E_1 \\ E_2 \\ E_3 \end{bmatrix}$$

$$\begin{bmatrix} D_1 \\ D_2 \\ D_3 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 & 0 & d_{15} & 0 \\ 0 & 0 & 0 & d_{24} & 0 & 0 \\ d_{31} & d_{32} & d_{33} & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} T_1 \\ T_2 \\ T_3 \\ T_4 \\ T_5 \\ T_6 \end{bmatrix} + \begin{bmatrix} \epsilon_{11} & 0 & 0 \\ 0 & \epsilon_{22} & 0 \\ 0 & 0 & \epsilon_{33} \end{bmatrix} \begin{bmatrix} E_1 \\ E_2 \\ E_3 \end{bmatrix}$$

- Simplified to one dimension

$$S_1 = s_{11}^E T_1 + d_{31} E_3$$

$$D_3 = d_{31} T_1 + \epsilon_{33}^T E_3$$

Typical Material Constants

PZT 5H (Navy Type VI)

d_{31} (m/V)	d_{33} (m/V)	Elastic modulus (N/m ²)	Density (kg/m ³)	ϵ_{33}^T (F/m)	Curie temp (°C)
-320×10^{-12}	650×10^{-12}	6×10^{10}	7800	3.36×10^{-8}	230

$$+ \begin{bmatrix} 0 & 0 & d_{31} \\ 0 & 0 & d_{32} \\ 0 & 0 & d_{33} \\ 0 & d_{24} & 0 \\ d_{15} & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} E_1 \\ E_2 \\ E_3 \end{bmatrix}$$

$$d_{33} \sim 2 \times d_{31}$$

Since E is scaled by distance (V/m) field applied across thin dimension

Common Configurations

- Patch

- Generates /responds to plate and beam bending and tensile/compressive waves
- Unimorph and bimorph configurations

- Stack

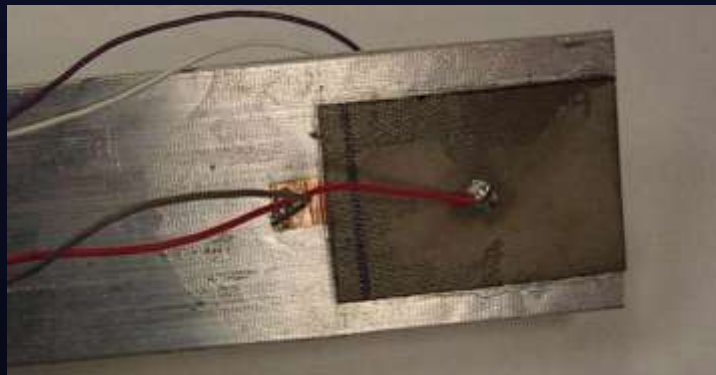
- Takes advantage of d_{33} coefficient

- MFC

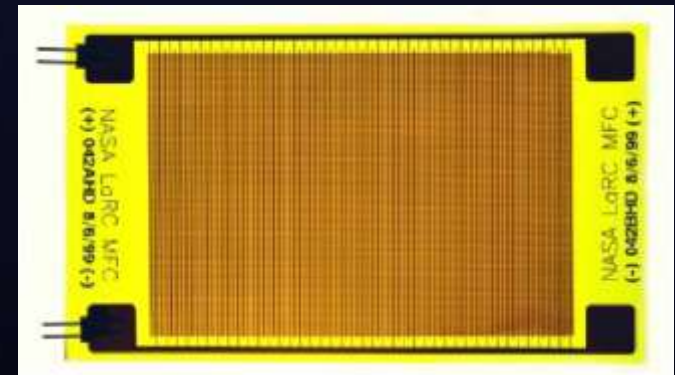
- Uses d_{33} coefficient for in-plane motion



Stack actuators from APC International
www.americanpiezo.com



Patch actuator



MFC actuator

Piezo Sensing/Actuation Examples



Sensing

- Accelerometer
- Power harvesting
- Passive damping – shunting (skis)



Actuation

- Atomic force microscope position control
- Speakers
- Buzzers
- Anything “ultrasonic” (humidifiers, cleaners)
- Depth finders/SONAR



Sensing/ actuation

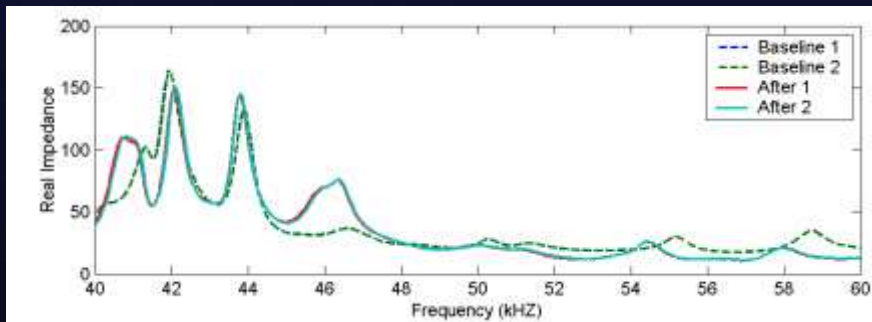
- Structural monitoring
- Vibration control

Current Fuzing Applications

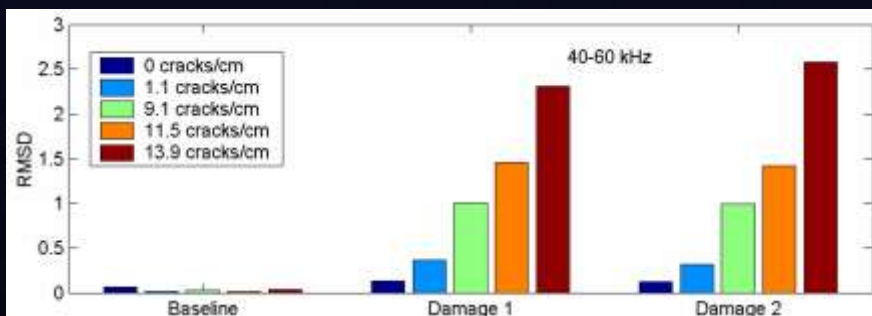
- Dozens of piezoelectric fuze patents
- Rocket Propelled Grenade
 - Acceleration at launch strains **piezoelectric fuze** that ignites primer.

Piezo-Based SHM

- Utilizes high frequency vibrations to detect local changes in materials
 - Stiffness changes due to cracking
 - Increases in damping
 - Interface changes such as loosening of a joint.
- Electrical impedance is directly related to mechanical impedance
- Wave propagation approach can also be utilized
 - Measure reflections, attenuation, delay due to damage



Impedance response



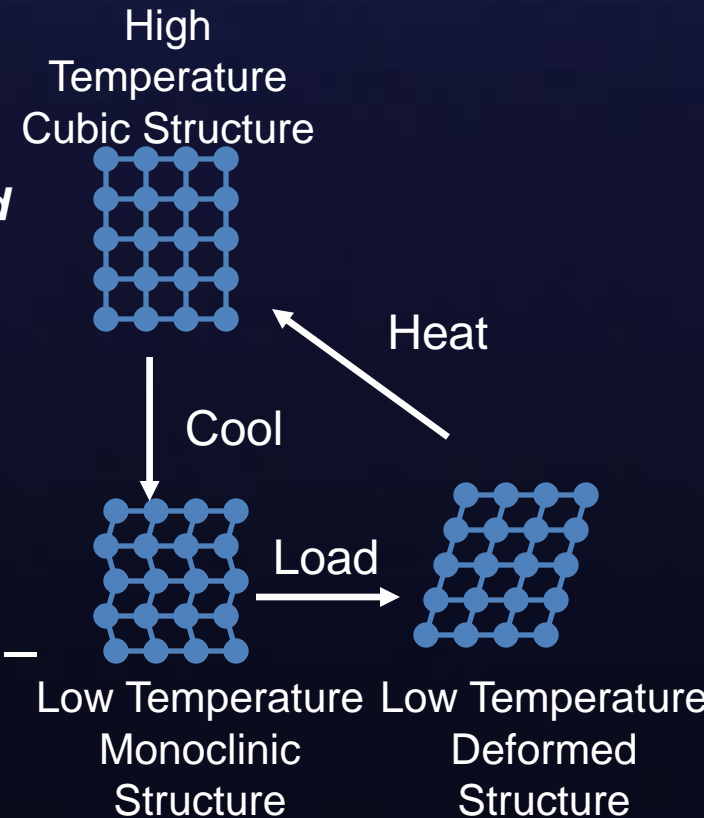
Damage Metric



Matrix cracking in carbon fiber composite

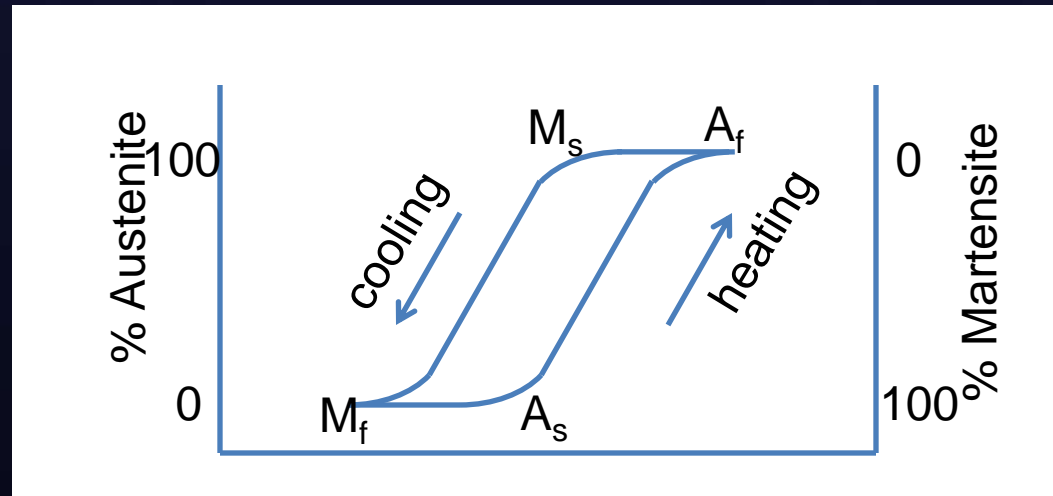
Shape Memory Alloy

- NiTiNOL developed at Naval Ordnance laboratory
- Shape memory effect : result of change in crystal structure
 - *Martensite at low temperature- twinned crystal structure*
 - *Austenite at high temperature- body centered cubic*
 - *Reverts to original undeformed shape when heated beyond transition temperature*
 - *One-way and two-way effects*
- Stress can also cause transition – Superelastic effect
- 6-8% strain
- Relatively slow response time
 - *Speed increased for low volume (faster temperature change)*



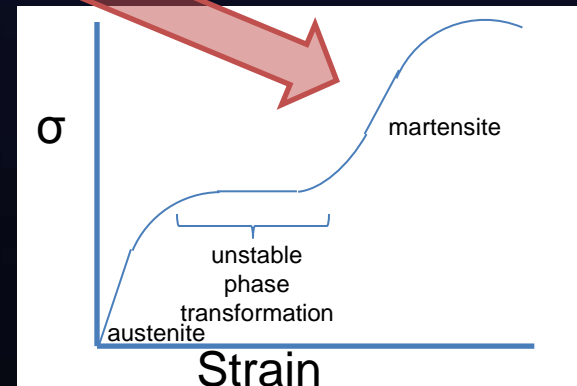
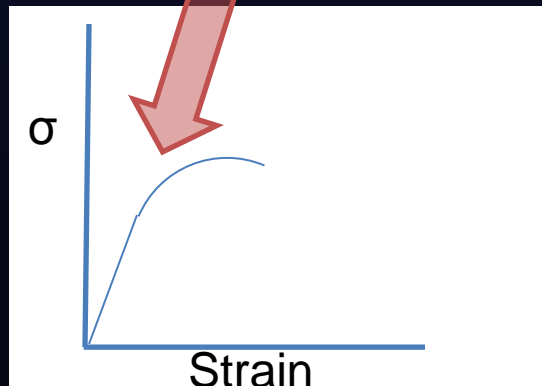
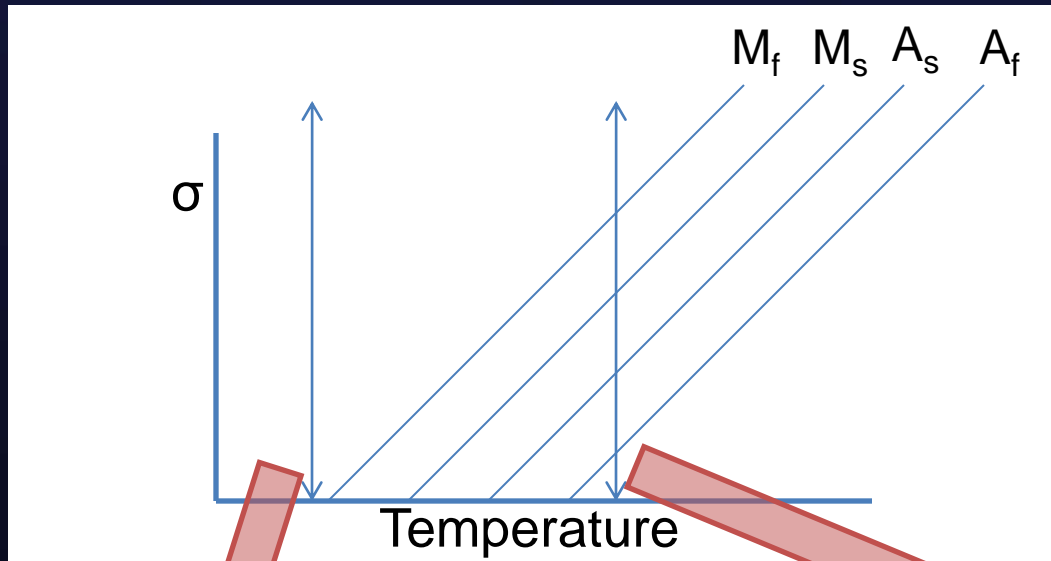
Temperature Transition

- Width and temperature of hysteresis can be controlled
- State dependent on path to current temperature



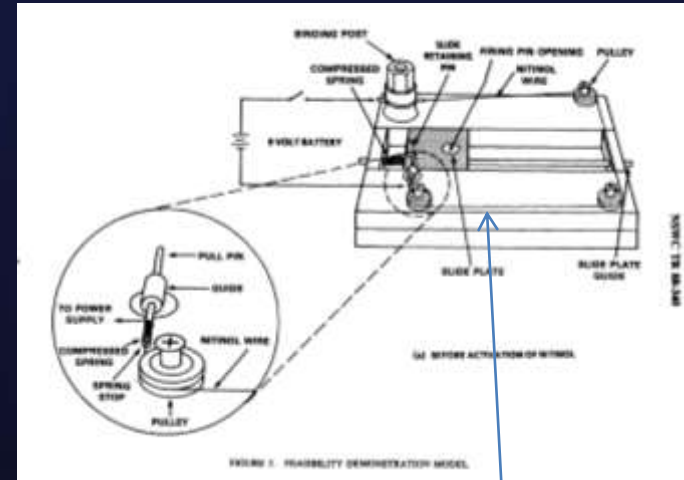
Superelastic Behavior

- Stress-strain curve depends on material temperature relative to transition temperature



SMA Fuzing Examples

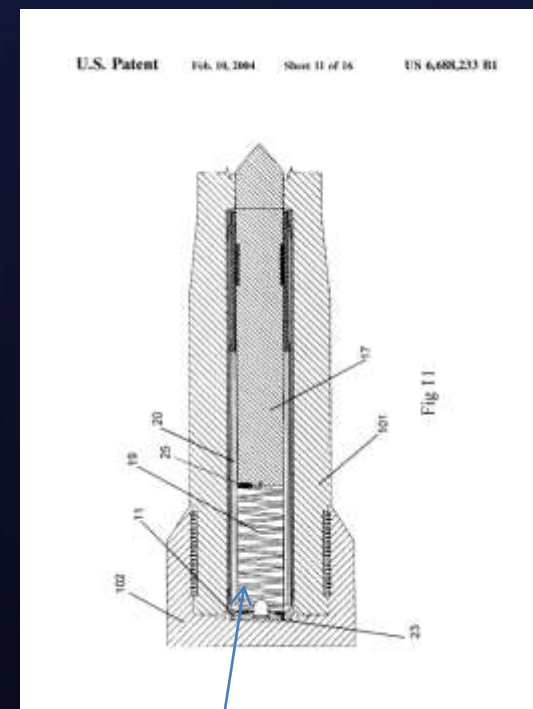
- Damping
- S&A actuation
 - *Goldstein and Weiner*
 - *Investigated effects of prestrain on transition temperature*
 - Activation temperature up to 150 C
- Non-pyrotechnic separation systems
- IM compliance
 - *Marchand et al. - Mine Clearance System rocket-towed linear demolition charge makeover*
 - *SMA proposed for release rocket motor case at both ends and actuate thermal igniter for Slow-Cook mitigation*
- Manufacturing
 - *Removable fixturing*



SMA wire

Reusable SMA Projectile Translation

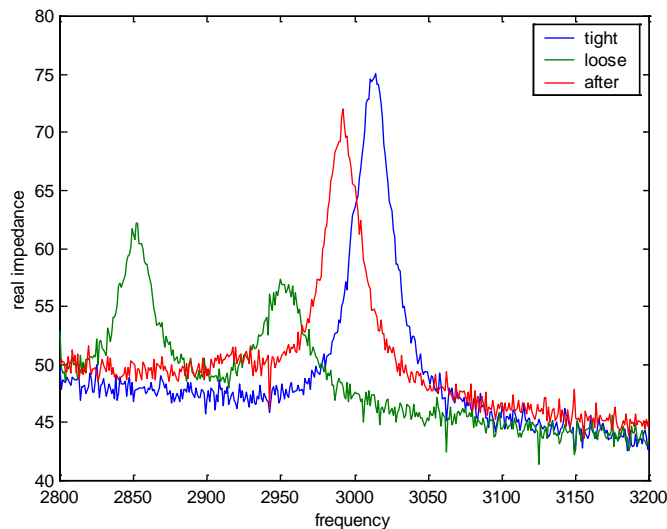
- Recoil, launch stress can be reduced by translating projectile a small distance forward prior to launch
- Typically accomplished by secondary charge
 - *Not reusable if launch is aborted*
- SMA spring suggested for Cased Telescoped Ammunition
- Manole et al. 2004 US patent 6,688233B1



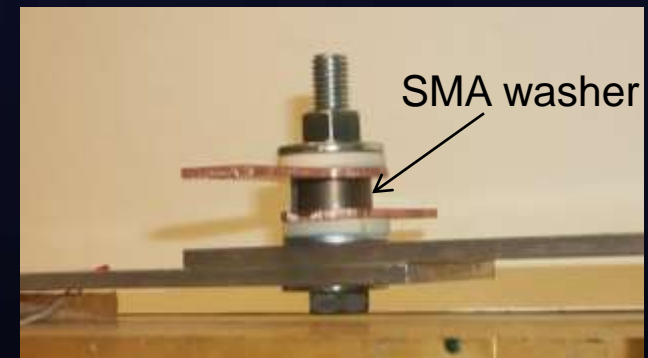
SMA spring

Self-Healing Bolted Joint

- Proof-of-concept testing
- Heated with external heater or resistively
 - *Competing for electrical and thermal isolation and high stiffness*
- Joint tightness monitored with PZT
- SMA ring sized to provide tension to compensate for reduced torque tightening



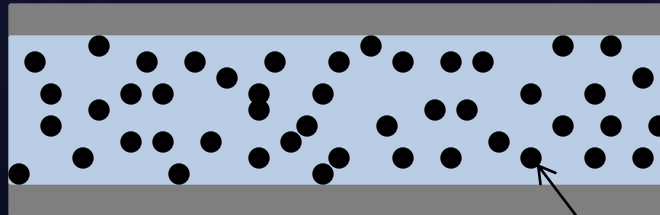
Impedance response of joint



Magnetorheological (MR) Fluids

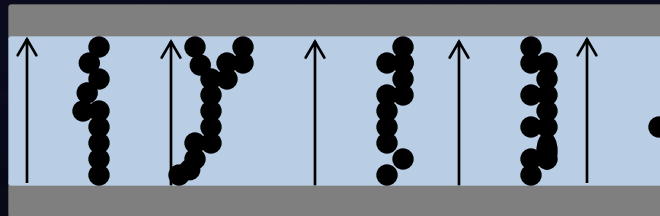
- Change viscosity with magnetic field
- Response times on order of 10 ms
- Viscoelastic solid below yield stress when field applied
 - *Field dependent modulus*
- Newtonian fluid when field is off

No magnetic field



ferromagnetic particles

Magnetic field present



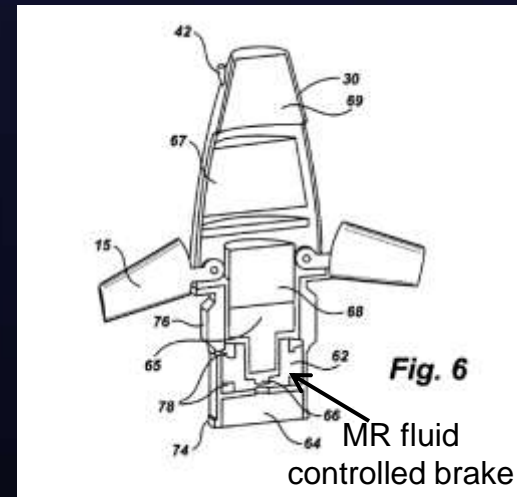
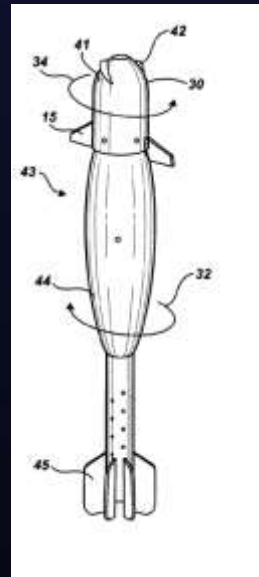
Possible Fuze Application

- Research on self-regulation of delay arming time of MR fluid fuze (Hu et al. 2010, Jiaxing University and Nanjing University of Science and Technology)
 - *Permanent magnet used to keep MR fluid as a solid during storage*
 - *Setback causes magnet to separate and rod impacts a piezo energy harvester*
 - *Energy harvester charges capacitor*
 - *Capacitor discharges into coil to regulate MR fluid viscosity*
 - *MR fluid viscosity controls flow through an orifice to control arm time*



MR Fluid Braking

- Morris et al., US Patent 7354017, 2008, Projectile trajectory control system
- Used to control de-spin of a projectile with braked rotating fins.



Summary and Conclusions

- Smart Materials offer alternative sensing and actuation systems
 - *Piezoelectric materials provide both sensing and actuation at high speed and forces, but low displacement*
 - *SMA provides high displacement and forces, but low speed*
 - *MR fluid provides fast response time and relatively high forces*
- Numerous unexplored applications for these materials exist including in the fuzing and ordnance environment

