



Use of a Synthetic Environment to Support Acquisition

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Introduction

- There is a growing use of **synthetic environments** to augment laboratory and field experiments that support the acquisition of improved military capability
- The synthetic environments can be used in several ways
 - To make the initial business case for a new acquisition program or to identify new lines of development
 - To shape the research program
 - To test and evaluate equipment
- Dstl's Virtual Battlespace has been used to support the acquisition program in areas including
 - Biological area detection
 - Low-burden protective clothing

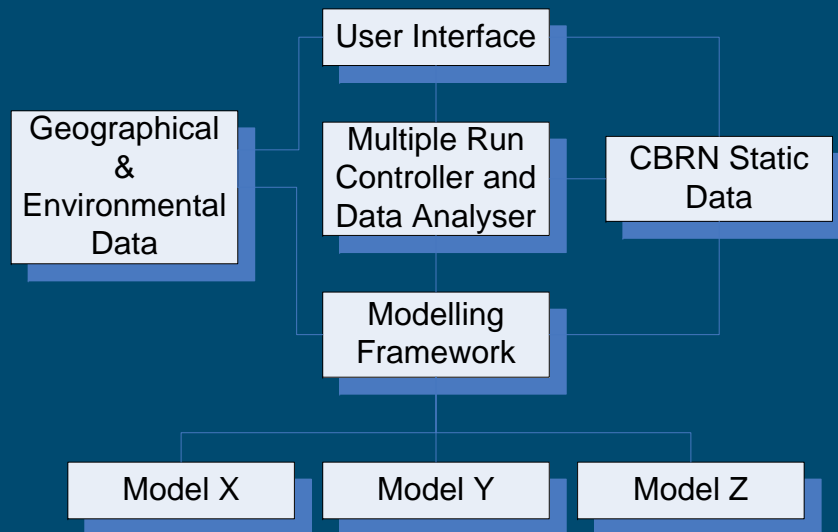
What is the Virtual Battlespace?

- A synthetic environment including (some under development)
 - State-of-the-art dispersion models (UDM & SCIPUFF)
 - Models of CBR defence system (detection, protection, MCMs)
 - Representation of movement of entities (aircraft, army units)
 - Links to combat & facility models (WISE, OneSAF, STAFFS)
 - Multiple run controller
 - Wargaming mode



The Virtual Battlespace Models

- Dispersion Modelling
 - CBR sources and hazard plumes (weapons, IEDs, RDDs, TICs & TIMs)
 - Urban and Rural (SCIPuff & UDM)
 - Concentration Realisation
- Meteorology
 - Terrain
 - Local Wind Turbulence
 - Sea Breeze



- Military Units/Personnel
 - Effects (casualties)
 - Inhalation & Contact Hazard (liquid pickup)
 - Medical Countermeasures
 - IPE
 - Physiological Burden
 - Aggregation
 - Value of Information
- Detectors
 - Simple (threshold)
 - Generic
 - Specific
 - Standoff
 - Biological Background
 - Single & Network Alarms
- Modes of Use
 - Wargaming
 - Assessment

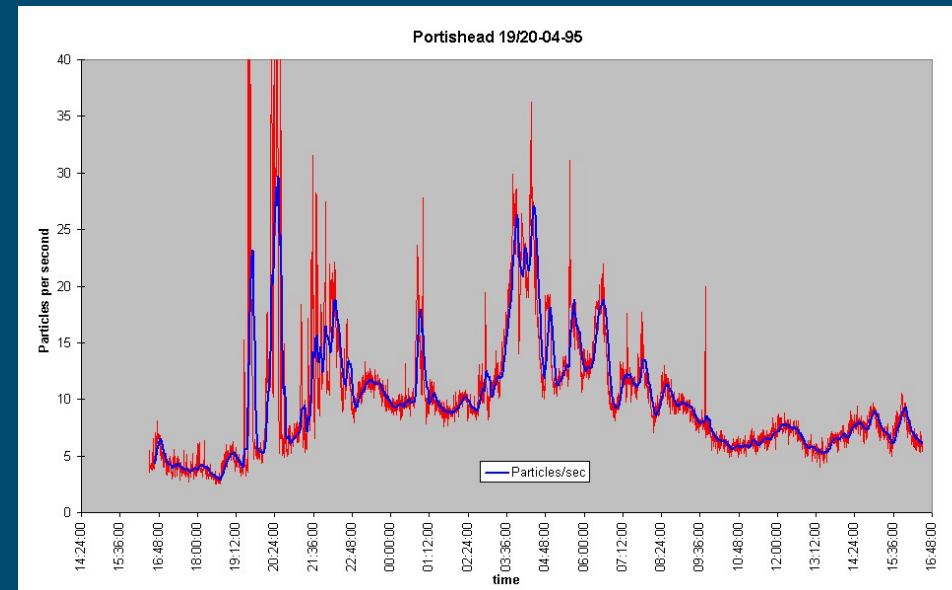
Biological Area Detection

- Previous work on acquiring the Integrated Sensor Management System
- Now a soft OA workshop study will define the concepts of use for an area detection capability
- This will quantify capability provided by networks of generic, specific and stand-off detectors in the CBVB
- Two main aims of the work:
 - Guide the research programme by estimating the performance of current and planned detectors
 - Allow stakeholders to make informed decisions by demonstrating what is and isn't feasible



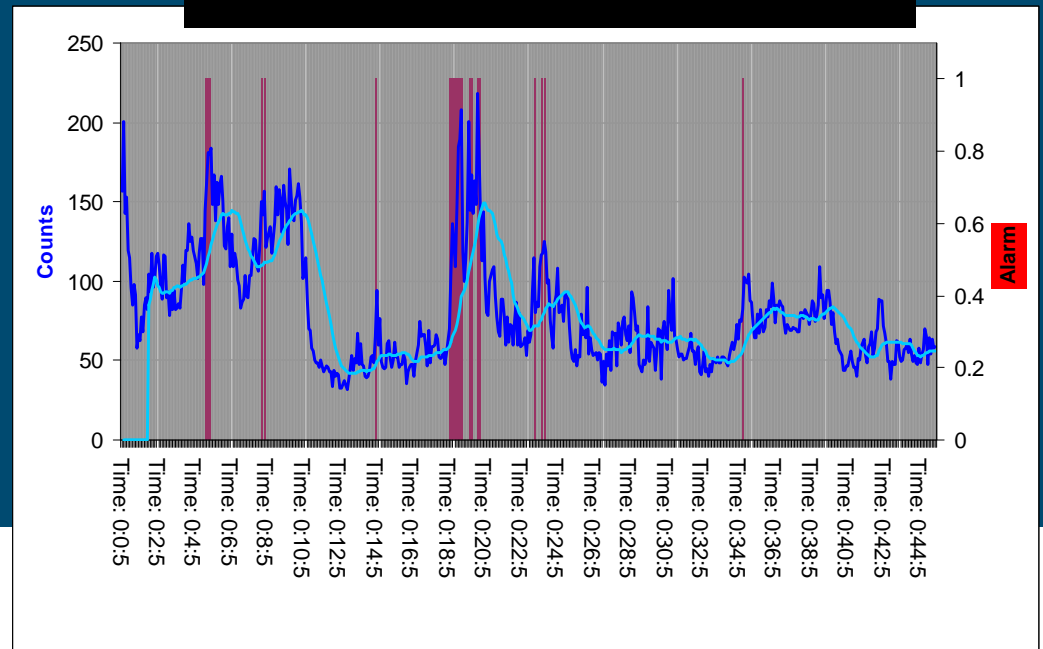
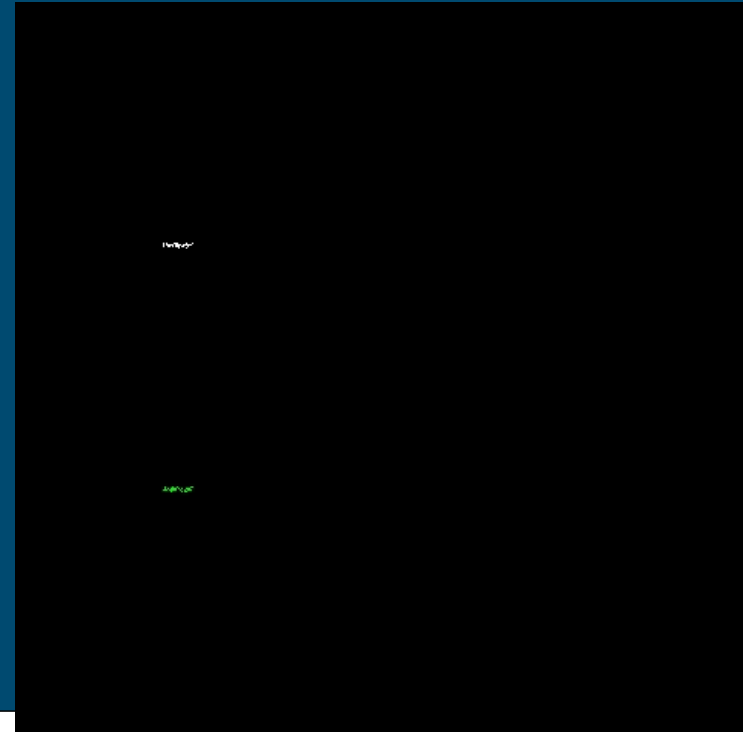
Integrated Sensor Management System (ISMS)

- Dstl supported the Defence Procurement Agency's assessment of systems developed by industry
 - Field trials expensive; detectors not available
- Therefore the assessment carried out in the Virtual Battlespace
 - Realistic simulation of biological background & turbulent, meandering plumes



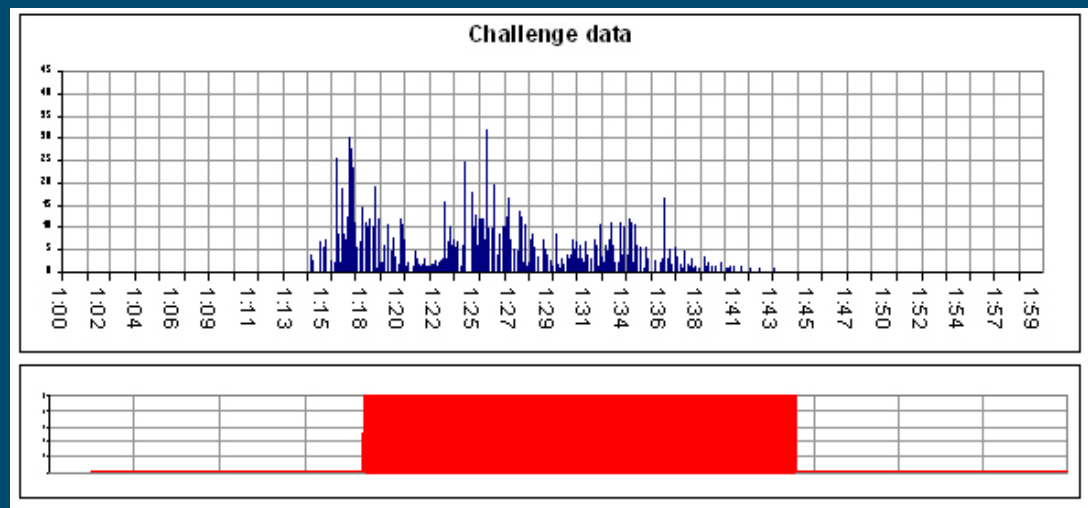
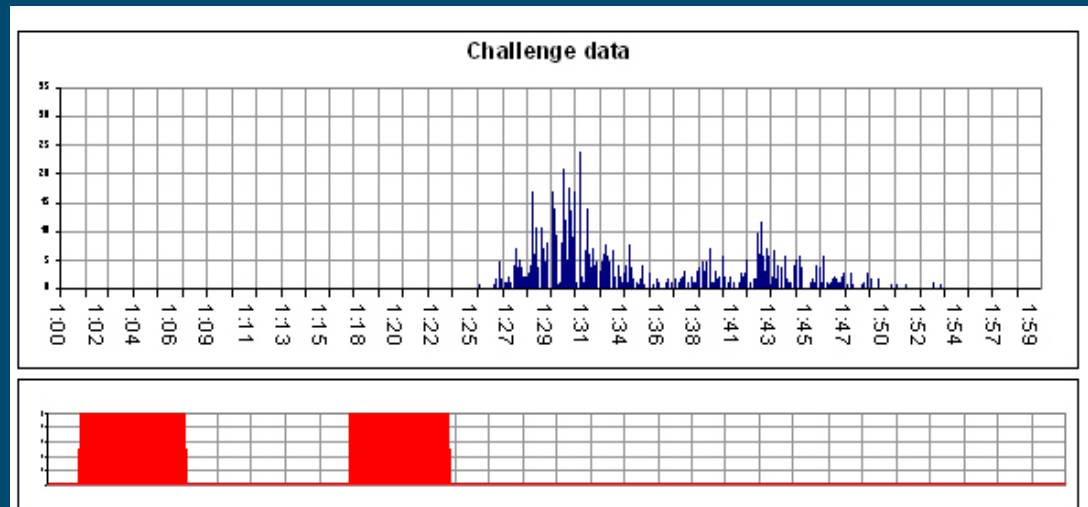
Modelling

- **Meander turbulence model** linked with UDM to provide a simulation of meandering plumes
 - required for realistic stimulation of detectors etc.
- **Biological background model** developed
 - based on field data
- **Generic biological detector models** developed
 - include measurement noise and sampling noise



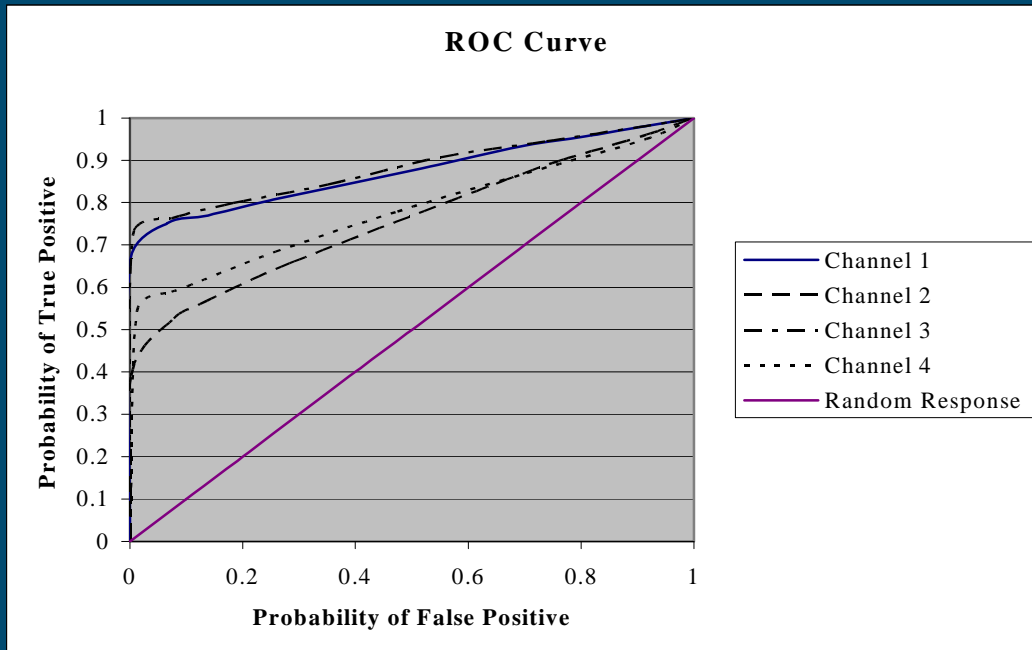
Outcome

- Successful study
 - Scored systems objectively
 - Guided number of sensors required
 - Assessed performance in difficult environments (rural, urban)



Sensor Networking

- Last year looked at networking WBS1 sensors using GARCH
- WBS1 network not sensitive enough but GARCH improved performance
- Plan to extend to other sensors and evaluate new and existing network fusion algorithms in the CBVB



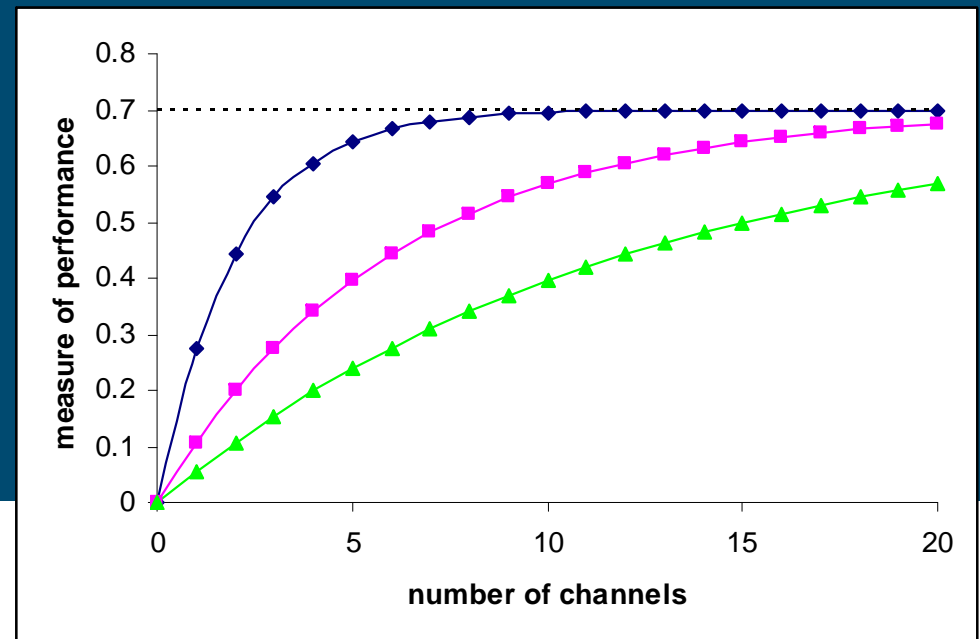
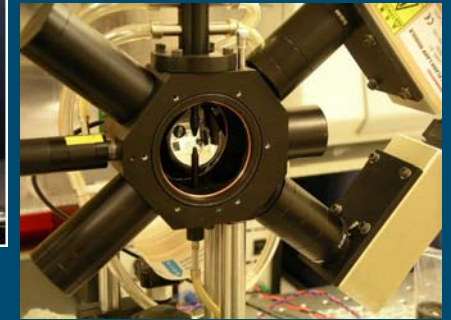
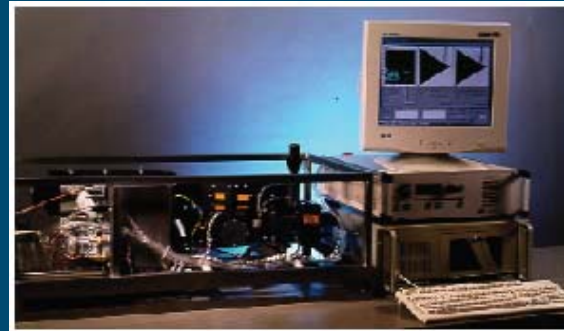
Task 1 – Improve ISMS Network Fusion

- ISMS uses the Biral VeroTect generic sensor & very simple network fusion algorithms
- GARCH network fusion algorithm shown to be effective on WBS1
- Compare effectiveness of ISMS algorithm and GARCH against model of VeroTect
- Results to feed into ISMS incremental update in March '07

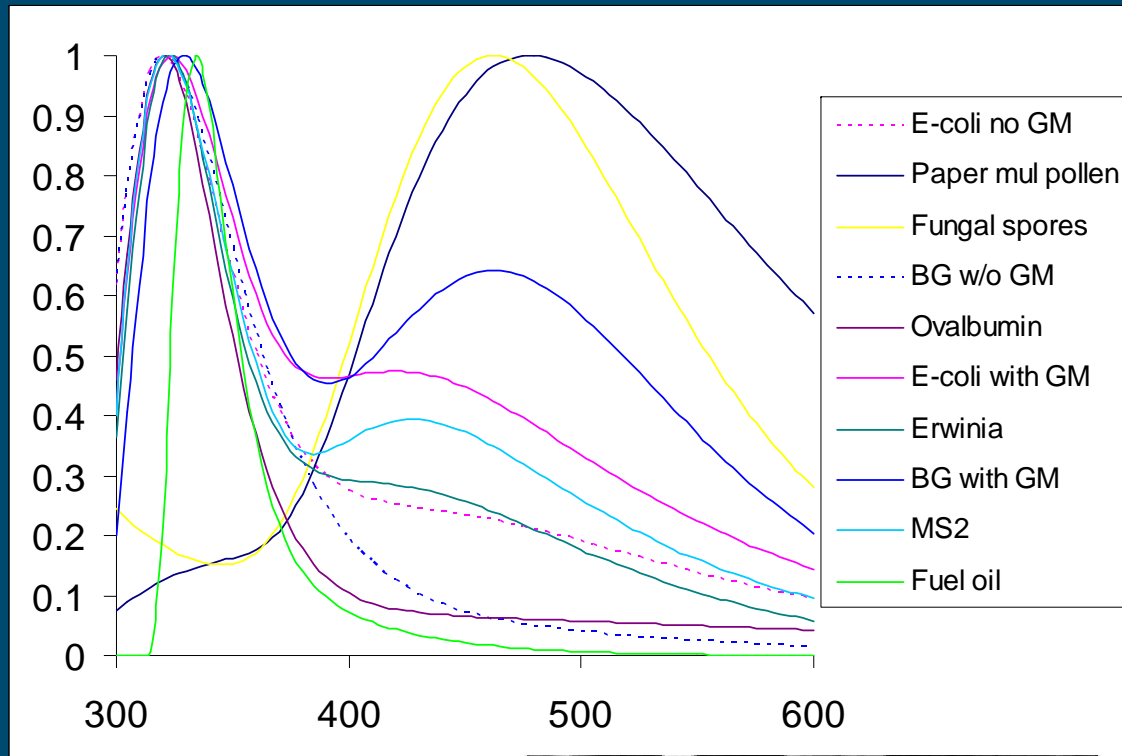


Task 2 – Find Optimal Generic Detector

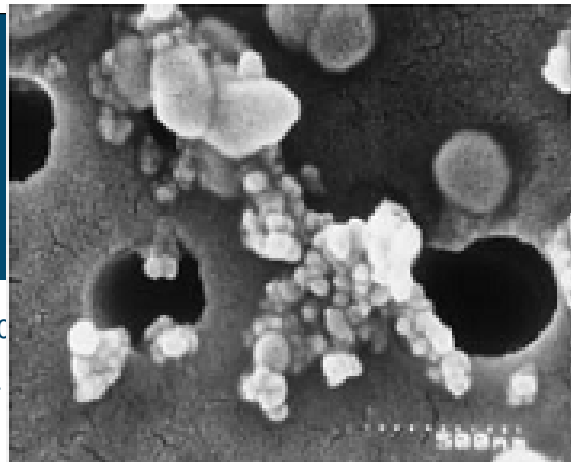
- Lots of different generic detector prototypes
- How much size, shape and fluorescence information before we approach maximum performance of a generic detector?



Task 2 – Find Optimal Generic Detector



- Size information important
- Fluorescence spectra contain 2-3 pieces of information
- Bulk fluorescence offers little discrimination – need fluorescence on a particle basis
- Crude shape information required (liquid spheres)



Aircraft & Aircrew CBRN Survive To Operate

- A large programme to procure CBR protective equipment for aircraft & aircrew
- OA used to determine
 - Is AACSTO necessary?
 - What air capability does AACSTO need to maintain?
 - What hazard levels are be involved in air operations?
 - What is the burden of AACSTO on aircrew?

AACSTO – Phase 1 - 3

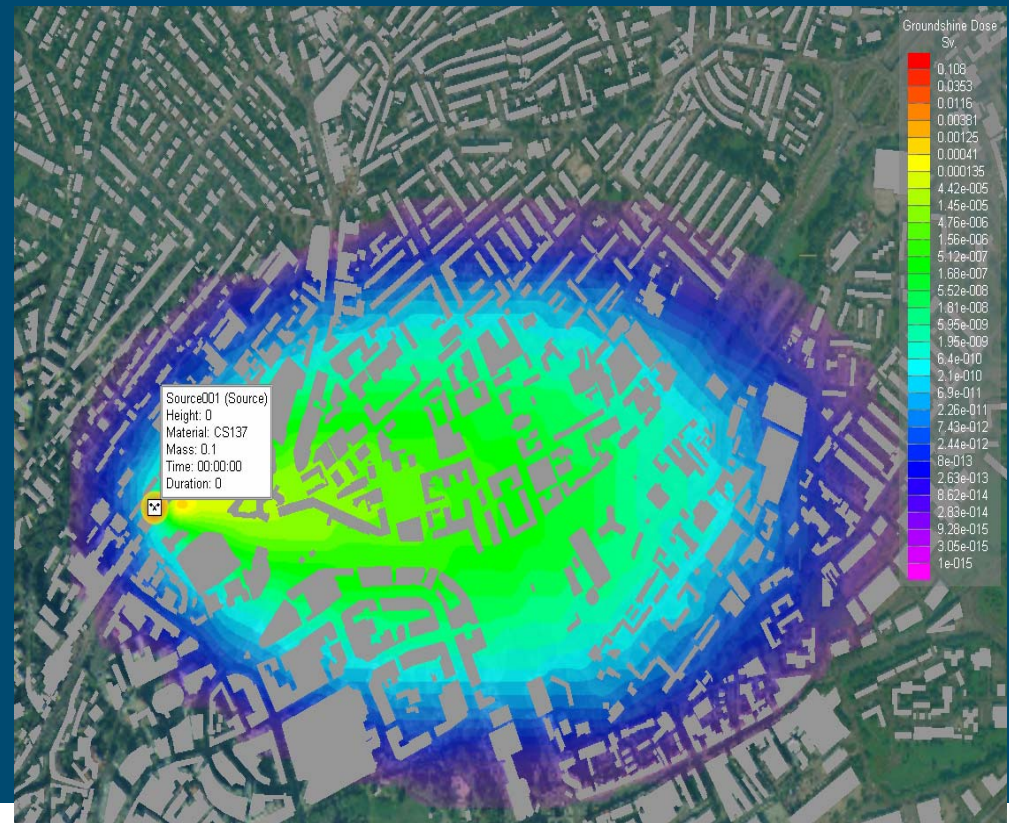
- Phase 1 - Complete
 - Review of existing work undertaken across MOD
 - Concluded that no work tested against comparable threats to those currently faced
- Phase 2 - Ongoing
 - Identify threat scenarios and use of CBRN materials
 - Determine the aircraft involved in these operations and their corresponding missions
 - Identify the concepts & doctrine used to mitigate the use of CBRN
- Phase 3 - Ongoing
 - Series of war-games and workshops to determine the areas in which AACSTO is most necessary

AACSTO - Phase 4

- Two main goals:
 - Quantify the CBR challenge that aircraft and aircrew may be exposed to
 - Determine the thermal load placed upon aircrew and ground-crew by a range of protective ensembles
- We use the aircraft, missions and threat scenarios that are coming out of Phase 2 (running in parallel)

The CBR Virtual Battlespace (CBVB)

- The CBVB is used for the modelling in Phase 4
- New models have been added to the CBVB as part of this work
 - Airframe Model
 - Heat Strain Model
 - Protection Model
 - Radiological Post Processor

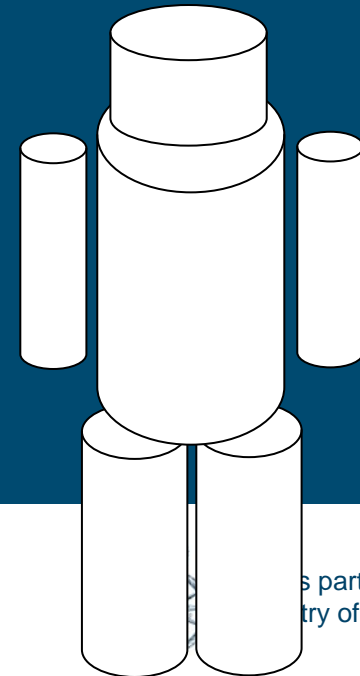
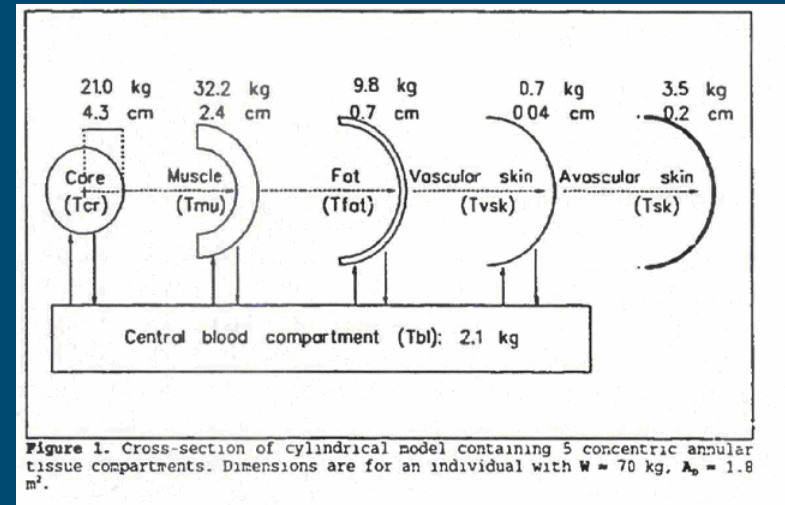


Task 1 – Draw up Mission Profiles

- Mission Profiles will include
 - Activity level (Watts)
 - Waypoints that describe route taken (either absolute or offset via velocity and start point (x,y,z,t))
 - Type of clothing represented as a protection factor and thermal and vapour resistances
 - Local environmental conditions, including temperature, winds & stability
- Take into account different phases:
 - Aircrew at rest on airbase
 - Transference to air platform
 - Take off
 - Level flight at representative height
 - Landing

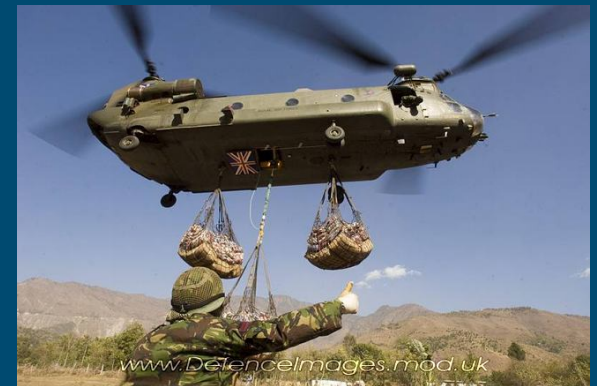
Task 2 – Safe Core Temperature

- Do mission profiles from Task 1 result in safe core temperatures?
- The Heat Strain Model
 - Based on US SCENARIO model, but improved
 - Now passed V&V testing
 - Is being compared against other models
 - USARIEM model
 - DSTO Werner/Lotens model
 - QinetiQ model
 - Also compared against experimental data

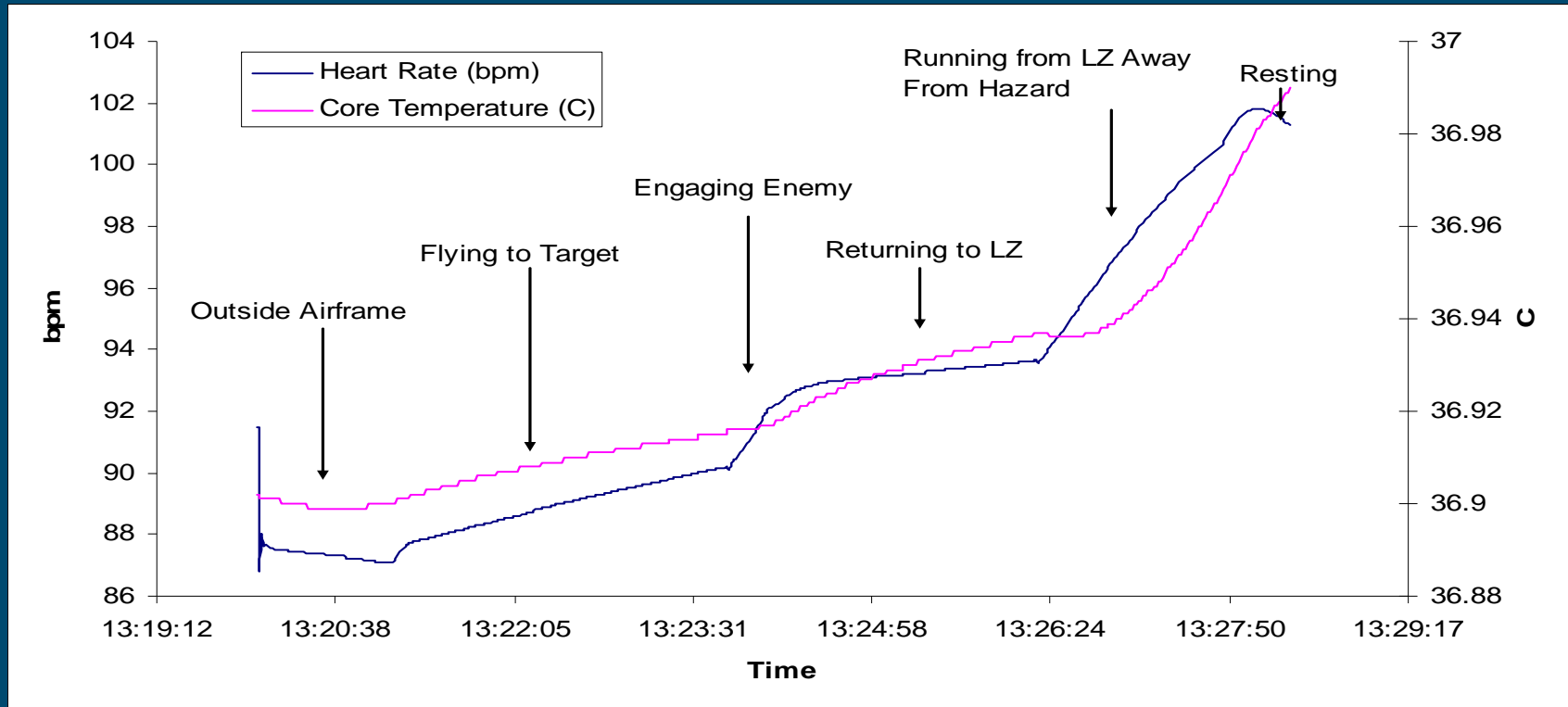


Task 2 – Safe Core Temperature

- The Airframe Model
 - Estimates the environmental conditions inside aircraft (radiant and ambient temperature, humidity & wind-speed)
 - Based on lit search of past trial data & simple atmospheric physics
 - Now integrated into the CBVB
- CBVB can calculate the heat strain associated with current and prototype clothing ensembles
 - Drive future clothing research



Task 2 – Safe Core Temperature



Task 3 – Determine CBR Challenge

- The Protection Model
 - New model to determine the protection factors provided by various types of aircraft now integrated into CBVB
- Predict the CBR hazard to the platforms at various times during the mission profiles:
 - Given that a CBR event is intercepted, determine if a high or low burden protection option is required, and when during the mission it is needed
- Mission profiles from Task 1 against current threat scenarios
 - Use of agent, weapon system and target will be derived from CBR planning scenario development work
 - Meteorological data specific to the location
- Challenge model runs completed for helicopters – fast jet and fixed wing runs underway.

Conclusions

- The Virtual Battlespace has been successfully used to support the acquisition process
 - Used to both test and evaluate existing capability and drive research in new areas
 - Significantly improved capability (includes casualty chain, effects on operations)
 - Widely used (2004-05 – 1 study; 2006-07 – 5 studies)
 - Every study improves VB, benefiting subsequent studies
 - International
 - New TTCP CBR Group AG
 - DSTO involvement