Evaluation of System Effectiveness of Guided Projectiles

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Typical Application

• <u>The Problem:</u>

 Assess the system effectiveness of a notional guided projectile (performance metrics = CEP).

• <u>Givens:</u>

- The basic projectile shape is known and the control mechanism (scheme) has been defined.
- The aerodynamics are unknown.
- The G, N, & C system has not yet been developed / defined.
 (e.g. "on" time, control force magnitude, etc.)

• <u>Output:</u>

- Calculate the CEP for a number of zones, ranges and atmospheric conditions....
- Delivery: one week!!!



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Guided System Simulation: Overview

Typical Monte Carlo Trajectory Simulation except:

- Want to refine guidance algorithms
- Compare Guided versus Unguided
- Do initial G,N, & C trades w/o "true" random draws
- Preprocessor module: develops a set of initial condition deltas from the error model
- Initial conditions "set" can be used repeatedly to isolate the influence of flight control system modifications
- IC "set" is expressed as deltas, applied to varying nominal cases (e.g. different zones or QE)



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Guided System Simulation: Overview



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Arrow Tech Approach

- 1. Build (or import) a model into PRODAS.
- 2. Estimate aerodynamics using one (or more) of the **PRODAS Aero Predictor** codes
- 3. Design the control system using the <u>**PRODAS GN&C</u>** <u>**Prototype Tool**</u></u>
- Define an error budget and create a set of initial conditions deltas using <u>PRODAS Initial Conditions</u> <u>Generator.</u>
- Define all of the nominal firing conditions, use <u>PRODAS Firing Table</u> module to solve for req'd QE and azimuth
- 6. Use the <u>**PRODAS Macro language</u>** to simulate thousands of firings with and w/o guidance.</u>
- 7. Process the results in spreadsheet.



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Step 1 – Build a Model

• There are multiple ways to build a model

- Use the PRODAS Model Editor
- Import either DXF or IGES files
- Point and click on a bitmap of an existing projectile with the PRODAS Tracing Tool
- Modify one of the existing models



 The model then becomes the basis for all of the subsequent analyses



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Step 2 – Estimate the Aerodynamics

- Use one or more of PRODAS' <u>Aero Prediction</u> codes
 - Spinner2000
 - Finner2000
 - AP98
 - Missile DATCOM
 - NEAR MISL3 (coming soon)



 If multiple codes are applicable, use the <u>Aero</u> <u>Manager</u> to help sort them out.



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Step 3a – Develop a Control System

- The <u>PRODAS GN&C Prototype Tool</u>
 - Fully integrated 6 DOF Trajectory and GN&C Simulation
 - Short learning curve w/ drag and drop control builder
 - Large library of control element building blocks, including typical sensors
 - Executes much faster than real time, depending on the size of the control system
 - Control with canards, squibs or generic forces and moments





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Step 3b – Build the GN&C System

Iteration 1

- Clean sheet design using projectile state variables
- No sensor errors
- Evaluate guidance algorithms and control loops
- Establish initial gains within the controller

Iteration 2

- Add realistic sensors with errors
- Work around sensor limitations (GPS slow updates)
- System tuning
- Test and tune with multiple nominal trajectories prior to Monte Carlo simulations



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Step 4a – Develop an Error Budget

- Develop an error budget for the system
 - Mission to Mission
 - Weapon to Weapon
 - Round to Round

| Error Source | Level of Application | | |
|-------------------------|---------------------------|------------------|-----------------------|
| | Mission-to-Mission | Weapon-to-Weapon | Round-to-Round |
| Gun Lay/Pointing/Aiming | | Х | |
| Gun/Weapon Dynamics | | Х | Х |
| Muzzle Velocity | Х | Х | Х |
| Ammunition / Projectile | Х | Х | Х |
| MET Staleness | Х | | |
| Weapon Location | | Х | |
| Fire Control | Х | | |
| GPS | Bias | | Random |

• Error Budget "Tuned" to match FT / "Real" World



Step 4b – Generate a Set of Initial Conditions Deltas

- Using the error budget and the <u>PRODAS Initial</u> <u>Conditions Generator</u>, generate error deltas for:
 - Muzzle Velocity
 - Angular Rates
 - Gun Pointing (QE and Azimuth)
 - Drag and Lift
 - GPS bias errors
 - Met variability
- These deltas are applied to a set of nominal values to provide IC's all of the subsequent runs.



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Step 5 – Define Gun Nominal Conditions

- Need the firing solutions for multiple ranges and zones
- Easiest way: run **PRODAS Artillery Firing Tables**



Step 6a - Build the macros

- PRODAS Macro language facilitates automation of just about anything a user can do.
 - Open a projectile file
 - Set the initial values for analysis
 - Run an analysis
 - Save a projectile file
 - Produce cross plots
 - Save results to a text file

• Or, use the <u>PRODAS Analysis Bot</u> to create the macro, which can be modified later if req'd.



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Step 6a' - Test the Macro





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Step 6b – Run the Macro

- For system simulations, we use a macro with two loops
 - The "inner" loop
 - Opens files
 - Runs guided 6 DOF Trajectories with random initial conditions
 - Collects Impact Data

- The "outer" loop

- Allows running "batches" of guided 6 DOF Trajectories with varying scenarios (e.g., zone, QE, Met, etc.)
- Build equations into the results file to calculate CEP



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Typical Guided Projectile Flight Behavior





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Step 7 - Post Process the Results

- All results are written to files for further processing / plotting.
 - Impact location and conditions, and initial conditions are recorded.
 - Intermediate data / states can be recorded.



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Example Outputs



- (Typical) 100 Shots with and w/o guidance
- CEP with & w/o guidance as a function of range



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Observations

- Guidance for artillery projectiles: Range & Az. Error, ~ 30-50m, range & proj. dependent
- Range Extension dependent on control scheme & mechanization
- CEP Effectiveness at short ranges dependent on maneuver authority, signal acquisition & active time
- CEP as a percent of range shrinks for guided projectiles at longer ranges, up to max maneuver authority



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Conclusions

- Integrated, all inclusive analyses (e.g. PRODAS) is the most efficient way to conduct trades
 - Eliminates hand-off / translation problems
 - Macro Language is powerful & flexible
 - Macros used for all types of trade studies
- System effectiveness comparisons of configuration changes (aero's, algorithms, duration, etc.) can be quickly generated & an optimum scheme selected
- Guided projectile performance (e.g. CEP) can be evaluated in a timely manner, using readily available tools.



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