

DEFINING THE FUTURE

Design and Testing of the Spartan USV Mine Warfare Module **Urveillance** and econnaissance Navigation Systems Systems Integration 14 June, 2005 **Dr. Robert Mons** Sr. Advisory Engineer

Sr. Advisory Engineer Northrop Grumman Corporation

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- Spartan USV and MIW Module
- Requirements
- AQS-14/24 Payload
- L&R Design
- Testing and Operation
- Conclusions





Spartan USV and MIW Module

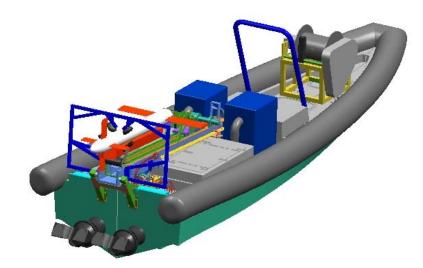
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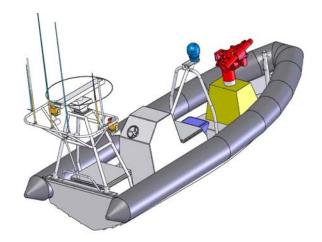


Spartan is Developing Three Modular Payloads

• 11 M RHIB









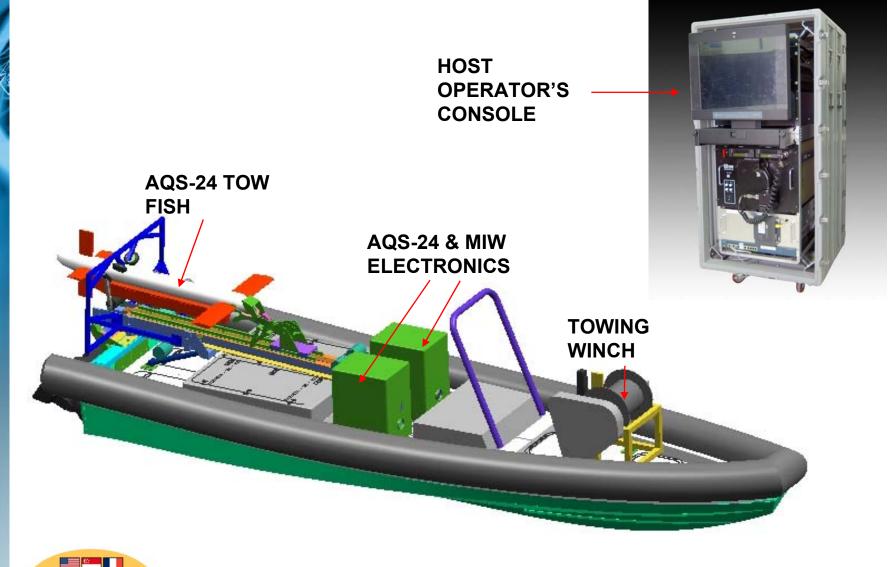
Subject of This Paper



- ISR & Force Protection
- ASW Module (French)



MIW Module Provides Capability for Remote Operation from USV





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Spartan USV and MIW Module Requirements AQS-14/24 Payload L&R Design Testing and Operation Conclusions





Key Requirements for MIW Module

- Modular design to facilitate interchangeability
- Positive restraint of towfish when stowed (for high speed transit)
- Semi-automated L&R control with future transition to "one button" and autonomous operation
- Weight limit of 3690 lbs
- Water Depths up to 200 Ft (170 Ft tow depth)
- Operate up to Sea State 3
- Maximize Area Coverage Rate (tow speed)
- Withstand wave slap load of 500 psf





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AQS-14/24 Tow Fish Is Suited To USV Operation

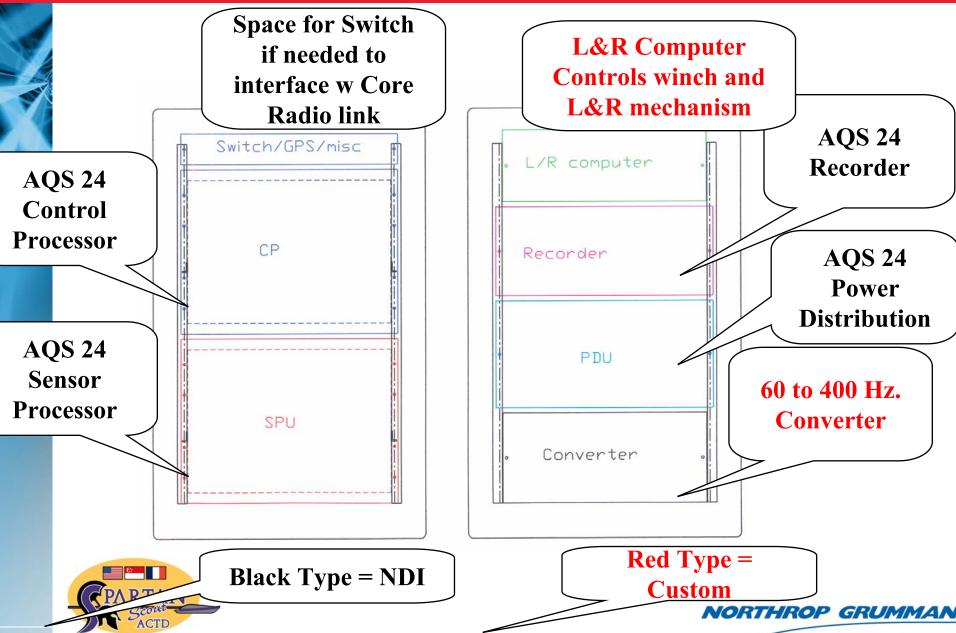
- High resolution SLS to detect & classify bottom mines
- 112 Inches L X 64 Inches W. Weight 550 Pounds
- Key features
 - Bottom tracking or constant depth modes.
 - Can operate at different SLS resolutions to accommodate radio link bandwidth.



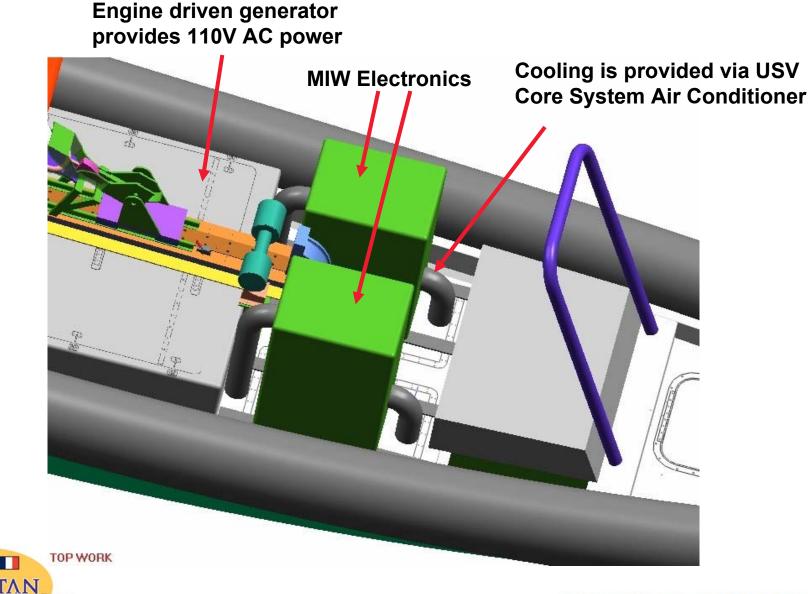




On Board Electronics Are Mostly NDI



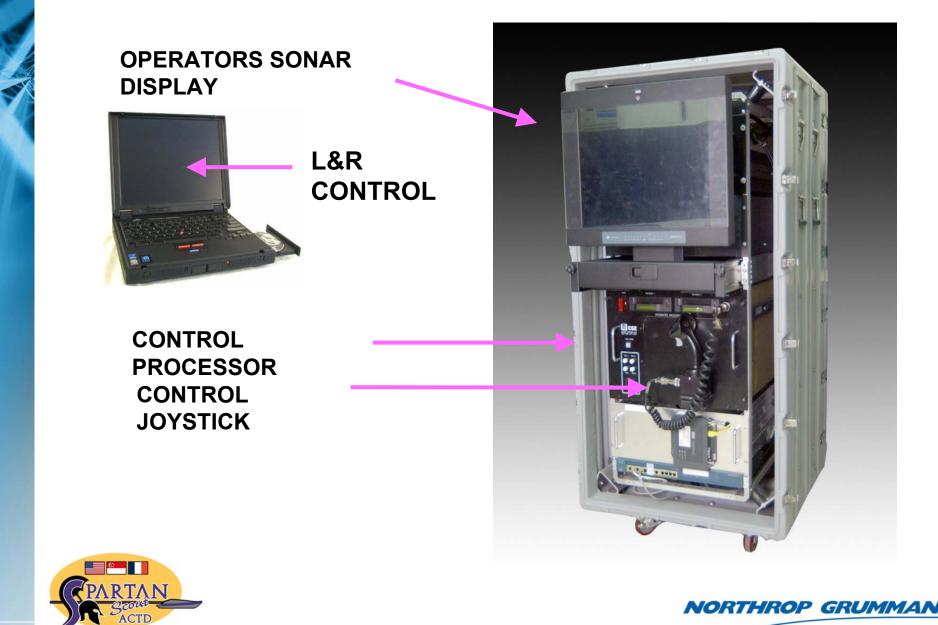
Electronics are Housed in Deck Mounted Ruggedized Cases





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Operators Console is Configured To Allow Location Flexibility

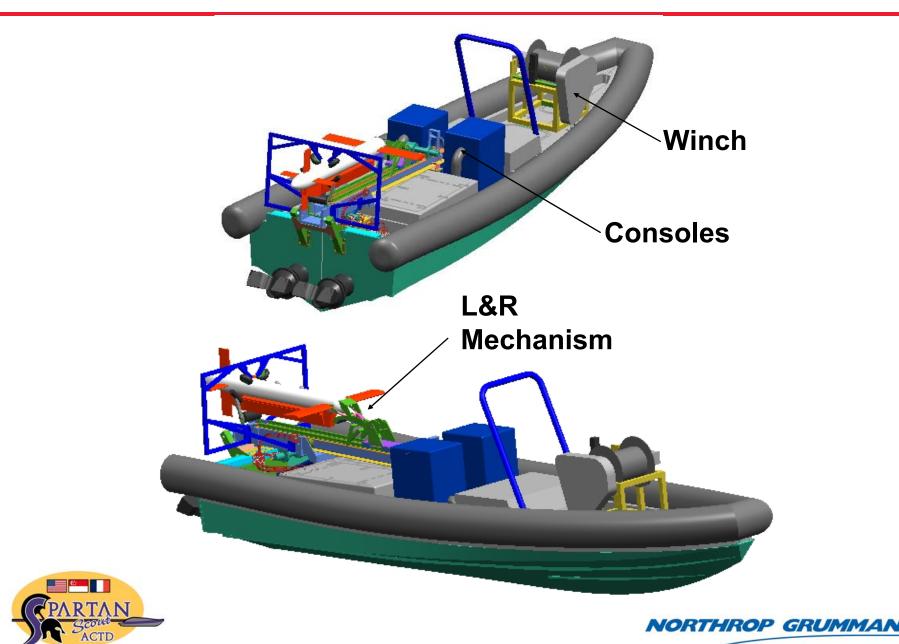


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General Arrangement



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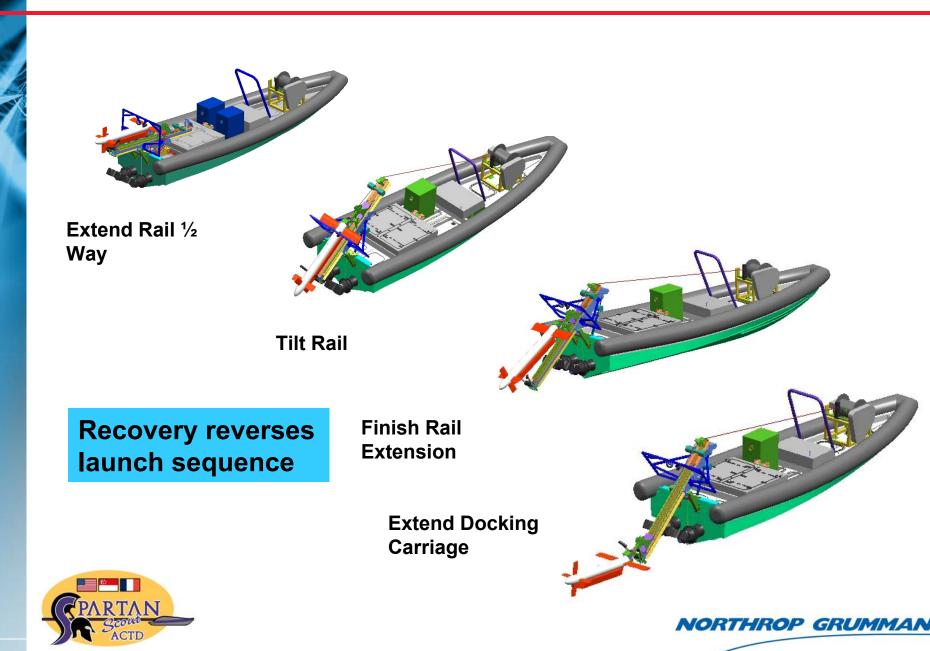
Key MIW – Craft Interfaces

- Primary Electrical Power from Core (117 VAC, 60 Hz At 6 KW
- Hydraulic Power for L&R and Winch from Core. 0 to 10 GPM at 3000 PSI <u>+</u> 10%
- Cooling Air for MIW Onboard Electronics from Core, 9000 BTU/hr and 400 CFM at $\Delta P = 1.3$ in. H₂O
- 3 Mbit/sec Uplink Bandwidth for Data Transmission
- Ethernet switch port at USV and host for command and status
- Video cameras NTSC input to video processor
- Foundations for Winch, L&R, and Electronics





Major Steps in L&R Deployment



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Spartan MIW Has Undergone Progressive Level Test Program

Builder's Trials March, 2005 in Chesapeake Bay

- Operation of L&R system
- Software & GUI refinement
- Craft manned
- Government Trials April, 2005 in Narragansett Bay
 - Conducted remote L&R operations
 - Data exfil via radio link
- Operational Demonstration
 - TBD In planning





Video of System Operation





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Conclusions

 MIW Module provides shallow water mine hunting capability from small unmanned surface craft

- Modular interfaces
- Positive tow fish restraint
- Within craft weight limit
- Semi-autonomous operation
- System is adaptable to variety of support craft
- Utility demonstrated in series of realistic operational tests



