



Unmanned Maritime Vehicle (UMV) Test & Evaluation Conference

Future Technology Development and Assessment for UUV Acquisition

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- T&E is part of an integrated technology development and acquisition strategy
- Early, effective use of Modeling and Simulation and HIL testbeds will add significant "value" and simplify the T&E process.
 - Creative solutions can be utilized to reduce cost



Demonstration UUV's



T&E of Payloads on UUV Testbeds

•Early Awareness of Fleet Integration Issues

- Common Interfaces and Modular Payloads
- •Applicable UUV Standards



<u>21UUV</u>

- ~ 200 In-Water Runs
- Acquisition Program Risk Mitigation
- Vision Based Navigation, Camera Suites, Photo Mosaic's
- Side Scan Sonar Imagery
- "Electric Torpedo" Testbed and Weapon Launch from MTV
- Autonomous Controller Experiments



MARV - Mid-sized Autonomous Research Vehicle

- Technology Demonstrations for Various S&T Programs
- Low Speed Control and Hover Payload (Thruster Based) Demonstrations
 - Imaging Sensor Evaluation
 - Homing and Docking Demonstrations



MTV - Manta Test Vehicle

- ~100 In-Water Runs
- Multiple UUV and Weapon Launch
- > Advanced ISR Suites RADINT, SIGINT, Optics, IR
- Deployed ASW Systems
- > Advanced Networked Communications
- > Advanced Autonomy







Creative use of Existing Navy Assets: ASW Targets



Partners: EMATT -Sippican Inc. Mk 30 Mod 2-TBD Sponsor: PMS404

 Provided 1073 training events with Mk 39 EMATT for FY 04

 Provided 314 training events in support of 446 customers with Mk 30 Mod 1 for FY 04



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 Received IOC approval letter for Mk 30 Mod 2
 -Production Contract Awarded (FY05)

Targets as UUV Mission Enablers?





*Expendable Mobile ASW Training Target (*EMATT)

- State of the Art Electronic Suite
- Dynamics
 - Submarine Realistic Turn Rates
 - -Run Speeds: 3-8 Knots
- Autonomous Evasion(AE)

 AE Cued by Torpedoes,
 Sonobuoys,
 Dipper, & Surface Ship
- Range Tracking Pinger Function
 - Addition of Mk 84 Long Ping Format
 - for Shallow Water



